

DE LA RECHERCHE À L'INDUSTRIE



Positive schemes for diffusion problems on deformed meshes

SimRace | Xavier Blanc, Jean-Sylvain Camier, François Hermeline, Emmanuel Labourasse

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- 1 Context
- 2 Construction
- 3 Secondary unknowns issue
- 4 Numerical results

Rosseland approximation hydro-rad system

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0^a, \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla(p + p_r) = \mathbf{0}^b, \\ \partial_t(\rho e + e_r) + \operatorname{div}((\rho e + e_r + p + p_r)\mathbf{u}) = \operatorname{div}\left(\frac{c}{3\sigma_R} \nabla e_r\right) + S^c. \end{cases}$$

^a ρ the density, \mathbf{u} the fluid velocity.

^b p the material pressure, $p_r = 1/3aT^4$ the radiative pressure, T the temperature.

^c $e = \varepsilon + 1/2\mathbf{u}^2$, the total material energy, $e_r = aT^4$ the radiative energy, c the speed of light, $\sigma_R(T)$ the Rosseland opacity, $\varepsilon(\rho, T)$ the internal energy and S the energy source.

Mathematical validity domain of this system

$$\rho > 0, \quad T > 0.$$

Splitting

- Splitting into a hydrodynamic part and a radiative part.
- Godunov-type Lagrangian scheme Glace ^a for the hydrodynamic part.

^aB. Després and C. Mazeran *Arch. Rat. Mech. anal.* 2005

We focus on the radiative part

$$\partial_t(\rho\varepsilon(T) + aT^4) = \operatorname{div} \left(\frac{c}{3\sigma_R} \nabla(aT^4) \right) + S.$$

Non-linear parabolic equation on T .

$$(\partial_T \varepsilon > 0, \partial_T e_r > 0, \sigma_R > 0, T|_{\Gamma} > 0, S > 0) \Rightarrow T > 0.$$

To conserve this property at the discrete level: need of positive (monotone) diffusion scheme.

- E. Bertolazzi et G. Manzini, A second-order maximum principle preserving finite volume method for steady convection-diffusion problems, SIAM, 2005.
- J. Droniou et C. Le Potier, Construction and convergence study of local-maximum-principle preserving schemes for elliptic equations, SIAM Journal on Numerical Analysis, 2011.
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¹Local-maximum-principle enforcement

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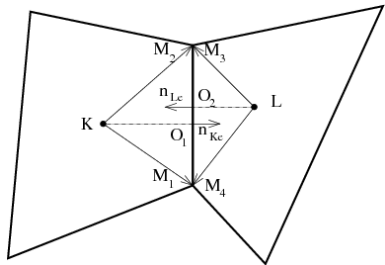
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Benchmarks (Samuel De Santis training 2010):

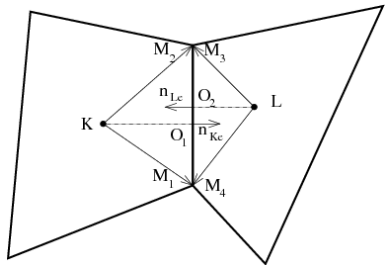
pro LMP¹ \Rightarrow positivity.

con LMP \Rightarrow more constraints on the non-linear system.

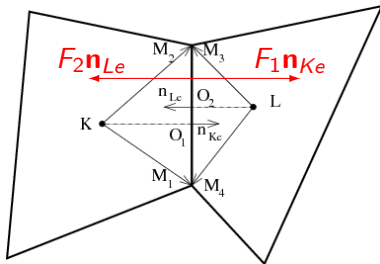
¹Local-maximum-principle enforcement



$$\int_K \frac{\partial u}{\partial t} dx - \int_K \nabla \cdot (\kappa \nabla u) dx = \int_K f dx,$$



$$\int_K \frac{\partial u}{\partial t} dx + \underbrace{\sum_{e \in \partial K} \left(- \int_e \kappa \nabla u \cdot \mathbf{n}_{K_e} d\Gamma \right)}_{\mathcal{F}_{K,e}} = \int_K f dx.$$



$$F_1 = \mathcal{F}_{K,e} + O(\Delta x^2)$$

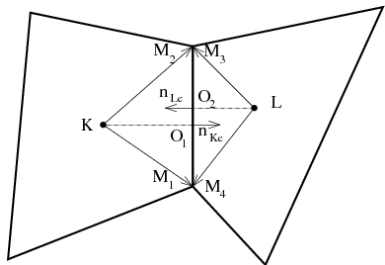
$$F_2 = \mathcal{F}_{L,e} + O(\Delta x^2)$$

$$\begin{aligned} \mu_1 F_1 - \mu_2 F_2 &= \mathcal{F}_{K,e} + O(\Delta x^2) \\ &= -\mathcal{F}_{L,e} + O(\Delta x^2) \end{aligned}$$

$$\forall \{\mu_1 \geq 0, \mu_2 \geq 0\}, \mu_1 + \mu_2 = 1$$

$$\int_K \frac{\partial u}{\partial t} dx + \sum_{e \in \partial K} \underbrace{\left(- \int_e \kappa \nabla u \cdot \mathbf{n}_{K,e} d\Gamma \right)}_{\mathcal{F}_{K,e}} = \int_K f dx.$$

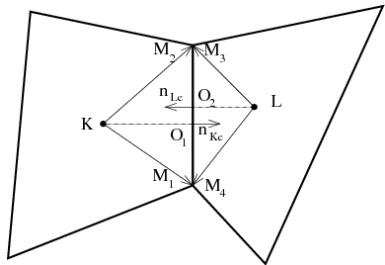
Building F_1 and F_2



$$\mathcal{F}_{Ke} = - \int_e \kappa \nabla u \cdot \mathbf{n}_{Ke} d\Gamma.$$

- Find $\{M_1, M_2, M_3, M_4\}$, s.t. $\mathbf{n}_{Ke} = \lambda_1 \mathbf{KM}_1 + \lambda_2 \mathbf{KM}_2$, $\mathbf{n}_{Le} = \lambda_3 \mathbf{KM}_3 + \lambda_4 \mathbf{KM}_4$ and $\lambda_1, \lambda_2, \lambda_3, \lambda_4 \geq 0$.
- $F_1 = -|e|\kappa_e (\lambda_1(u_{M_1} - u_K) + \lambda_2(u_{M_2} - u_K))$
- $F_2 = -|e|\kappa_e (\lambda_3(u_{M_3} - u_L) + \lambda_4(u_{M_4} - u_L))$
- $F_{Ke} = \mu_1 F_1 - \mu_2 F_2 = \mathcal{F}_{Ke} + O(\Delta x^2)$

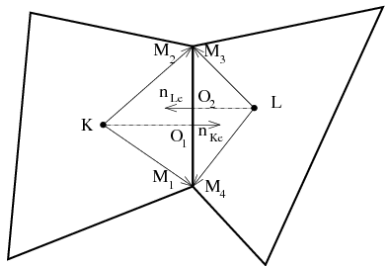
Calculation of μ_1 and μ_2



$$F_{Ke} = \mu_1 F_1 - \mu_2 F_2$$

$$F_{Ke} = |e| \kappa_e \left(\mu_1 (\lambda_1 + \lambda_2) u_K - \mu_2 (\lambda_3 + \lambda_4) u_L \right. \\ \left. - \underbrace{\mu_1 (\lambda_1 u_{M_1} + \lambda_2 u_{M_2})}_{a_1} + \underbrace{\mu_2 (\lambda_3 u_{M_3} + \lambda_4 u_{M_4})}_{a_2} \right)$$

$$\begin{cases} \mu_1 + \mu_2 = 1 \\ a_1 \mu_1 - a_2 \mu_2 = 0 \end{cases}$$



$$F_{Ke} = \mu_1 F_1 - \mu_2 F_2$$

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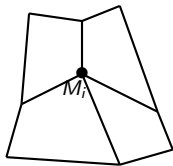
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We obtain

$$F_{Ke} = |e| \kappa_e (\mu_1 (\lambda_1 + \lambda_2) u_K - \mu_2 (\lambda_3 + \lambda_4) u_L)$$

$$\text{with: } \begin{cases} \mu_1 = \frac{a_2}{a_1 + a_2}, \mu_2 = \frac{a_1}{a_1 + a_2}, \\ a_1 = \lambda_1 u_{M_1} + \lambda_2 u_{M_2}, a_2 = \lambda_3 u_{M_3} + \lambda_4 u_{M_4} \end{cases}$$

- The scheme is non-linear,
- the scheme is positive iff $a_1 \geq 0$ and $a_2 \geq 0$.
- a sufficient condition for that is $u_{M_1}, u_{M_2}, u_{M_3}, u_{M_4} \geq 0$,
- the matrix obtained is non-symmetric,
- degenerate on TPFA scheme on cartesian grids.



Sheng, Yuan and Yue initial solution

Find three cell-centers geometrically surrounding M_i and perform a barycentric interpolation of u_{M_i} .

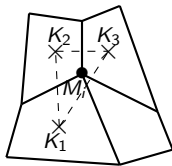
pro Second-order accuracy,

pro positive weights,

con If the mesh is heavily deformed, centers can be far from M_i (parallelism issue) and even not exist.

con Non unique.

ABANDONNED...



$$u_{M_i} = \omega_1 u_{K_1} + \omega_2 u_{K_2} + \omega_3 u_{K_3}$$

$$\omega_1, \omega_2, \omega_3 \geq 0$$

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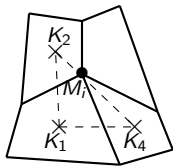
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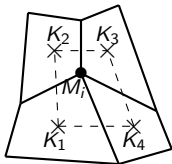
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$$\omega_1, \omega_2, \omega_3, \omega_4 \geq 0$$

Sheng, Yuan, Yue Modified (SY YM) Xavier Blanc, E. L., ZAMM 2015

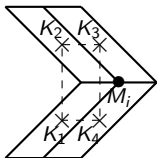
Use all cell-centers topologically surrounding M_i and perform a least-squares interpolation of u_{M_i} .

pro Second-order accuracy,

pro easy parallelism,

con If the mesh is heavily deformed, some weights can be negative.

Truncate negative u_{M_i} to zero (legal because we assume $u > 0$).



$$u_{M_i} = \max(0, \omega_1 u_{K_1} + \omega_2 u_{K_2} + \omega_3 u_{K_3} + \omega_4 u_{K_4})$$

some $\omega_j \leq 0$

Sheng, Yuan, Yue Modified (SYYM) Xavier Blanc, E. L., ZAMM 2015

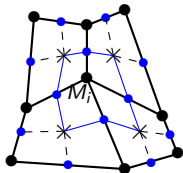
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pro Second-order accuracy,

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Truncate negative u_{M_i} to zero (legal because we assume $u > 0$).



$$\int \kappa \nabla u \cdot \mathbf{n} d\Gamma$$

approximated on the dual (blue) cell with the algorithm described before.

DDFV-like strategy , J.-S. Camier, F. Hermeline, IJNM Engineering, to appear

Solve a second diffusion problem on the dual mesh to compute M_i .

pro Second-order accuracy,

pro easy parallelism,

con number of degrees of freedom multiplied by two.

Called NLMDDFV in the sequel.

Properties

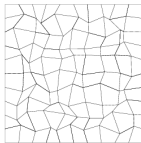
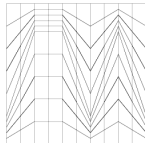
- Positive (for converged linear solver),
- conservative,
- non-linear (fixed point strategy required even for linear problems),
- existence of a solution,
- convergence to the solution under a parabolic CFL condition.

Associated matrices (backward Euler in time)

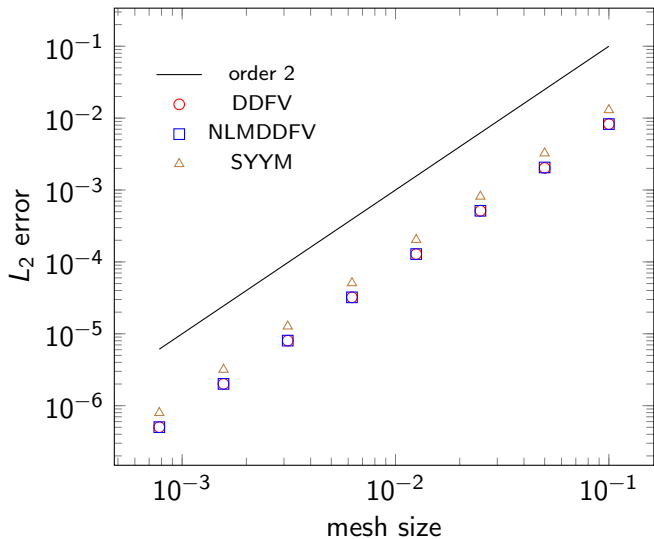
- Non-symmetric, M^T is a M-matrix,
- very sparse (only 5 non zero coefficients per row in 2D on structured square mesh).

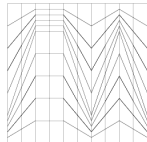
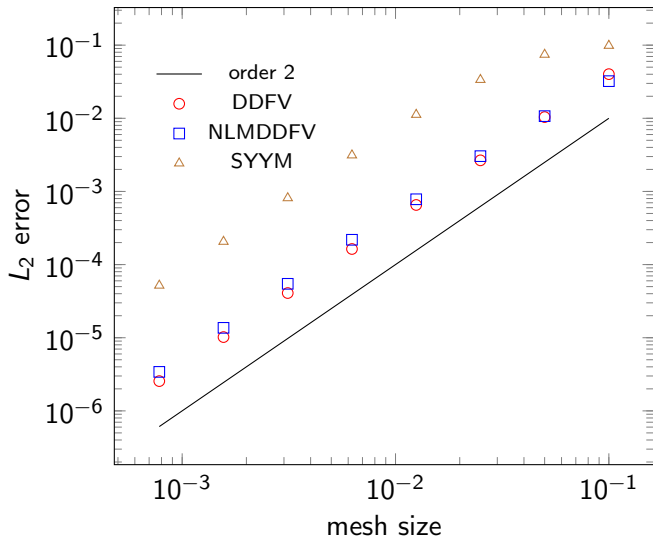
Initial and boundary conditions

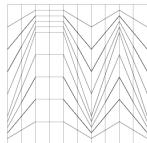
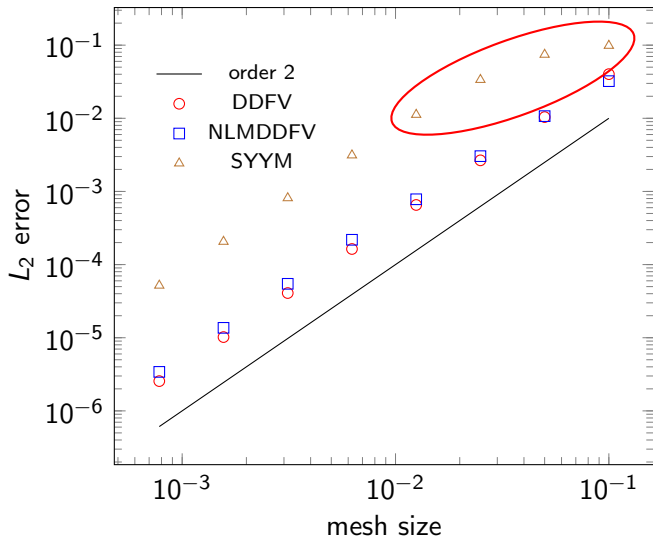
- $-\Delta u = 2\pi^2 \sin(\pi x)\sin(\pi y), u|_{\Gamma} = 0, \Omega = [0, 1]^2,$
- mesh convergency from 10^2 to 1280^2 zones,
- four mesh patterns.



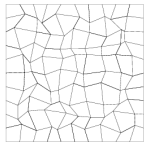
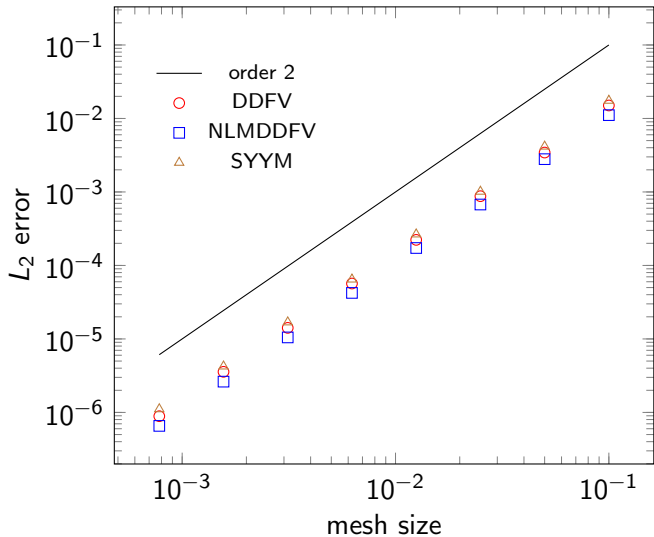
Steady analytic problem



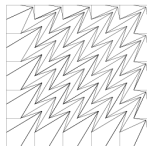
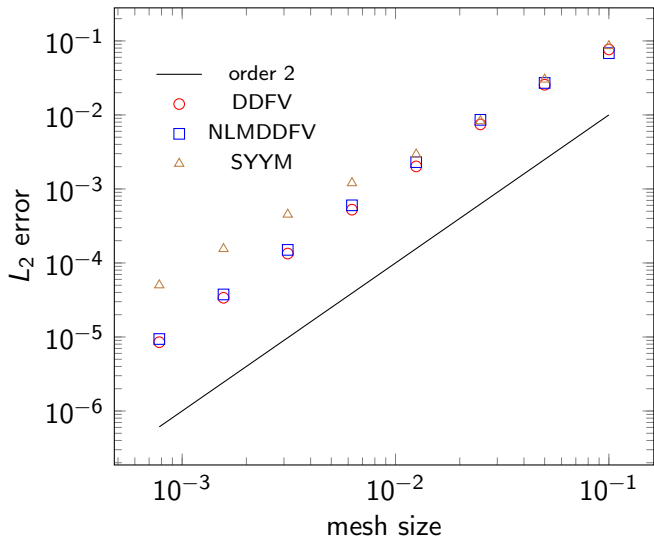




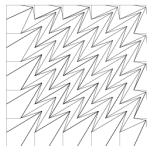
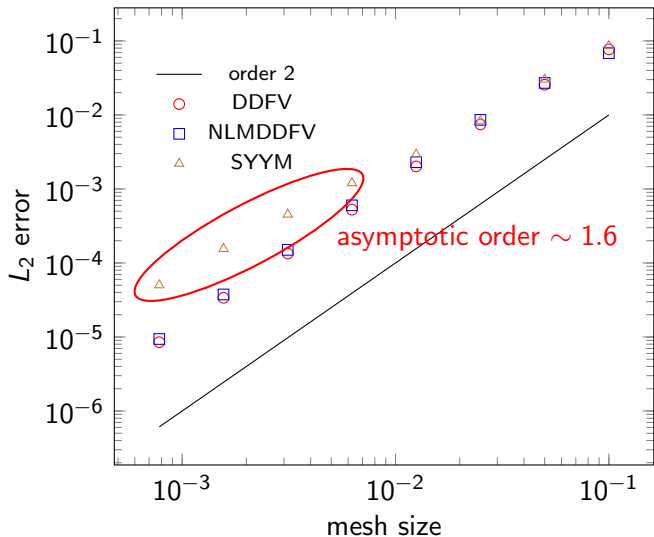
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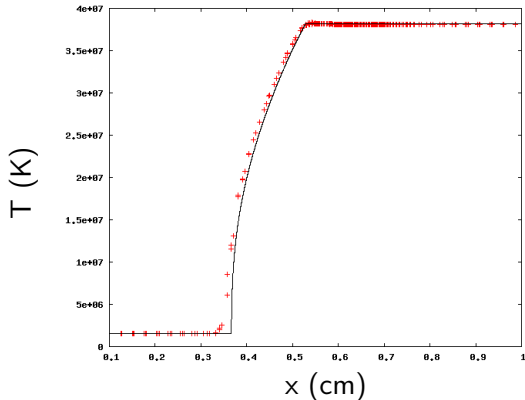
Steady analytic problem



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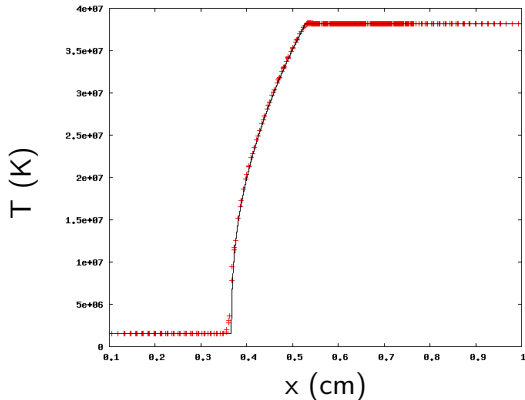
1D hydro-radiative problem with semi-analytic solution²
computed on kershaw mesh. Fails with mimetic schemes without fix.



+ numerical result
on 64×10 grid
— semi-analytic reference

²R. Lowrie and R. Rauenzahn, Shock Waves, 2007

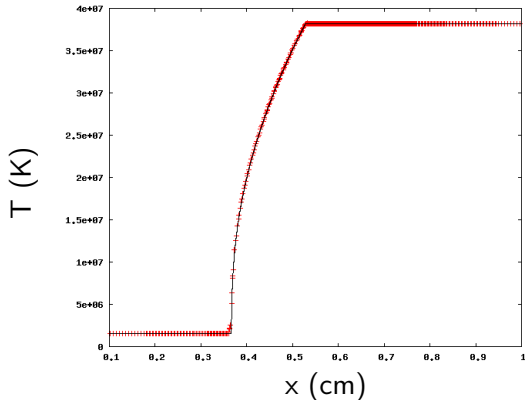
1D hydro-radiative problem with semi-analytic solution²
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+ numerical result
on 128×20 grid
— semi-analytic reference

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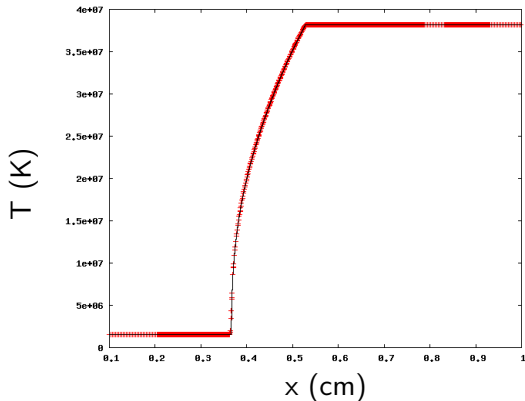
1D hydro-radiative problem with semi-analytic solution²
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+ numerical result
on 256×40 grid
– semi-analytic reference

²R. Lowrie and R. Rauenzahn, Shock Waves, 2007

1D hydro-radiative problem with semi-analytic solution²
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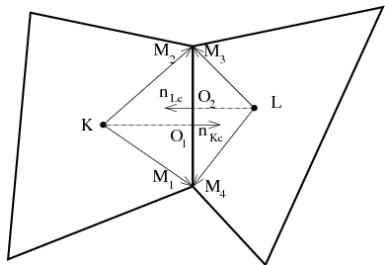


+ numerical result
on 512×80 grid
– semi-analytic reference

²R. Lowrie and R. Rauenzahn, Shock Waves, 2007

This kind of schemes widely increases the robustness of our calculations on deformed meshes.

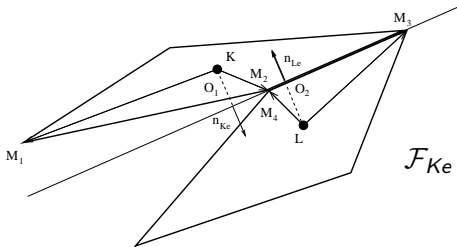
Building F_1 and F_2



$$\mathcal{F}_{Ke} = - \int_e \kappa \nabla u \cdot \mathbf{n}_{Ke} d\Gamma.$$

- Find $\{M_1, M_2, M_3, M_4\}$, s.t. $\mathbf{n}_{Ke} = \lambda_1 \mathbf{KM}_1 + \lambda_2 \mathbf{KM}_2$, $\mathbf{n}_{Le} = \lambda_3 \mathbf{KM}_3 + \lambda_4 \mathbf{KM}_4$ and $\lambda_1, \lambda_2, \lambda_3, \lambda_4 \geq 0$.
- $F_1 = -|e|\kappa_e (\lambda_1(u_{M_1} - u_K) + \lambda_2(u_{M_2} - u_K))$
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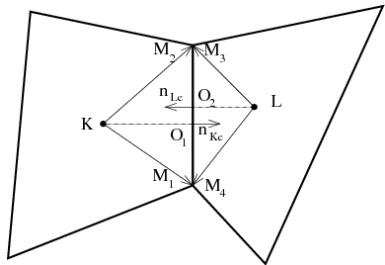
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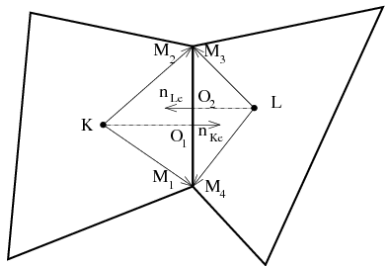
Calculation of μ_1 and μ_2



$$F_{Ke} = \mu_1 F_1 - \mu_2 F_2$$

$$F_{Ke} = |e| \kappa_e \left(\mu_1 (\lambda_1 + \lambda_2) u_K - \mu_2 (\lambda_3 + \lambda_4) u_L - \underbrace{\mu_1 (\lambda_1 u_{M_1} + \lambda_2 u_{M_2})}_{a_1} + \underbrace{\mu_2 (\lambda_3 u_{M_3} + \lambda_4 u_{M_4})}_{a_2} \right)$$

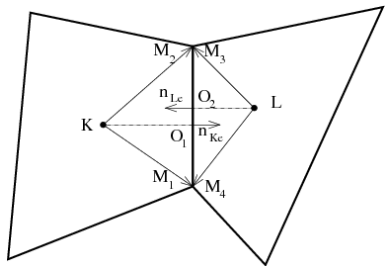
$$\begin{cases} \mu_1 + \mu_2 = 1 \\ a_1 \mu_1 - a_2 \mu_2 = 0 \end{cases}$$



$$F_{Ke} = \mu_1 F_1 - \mu_2 F_2$$

$$F_{Ke} = |e| \kappa_e \quad (\mu_1(\lambda_1 + \lambda_2) u_K - \mu_2(\lambda_3 + \lambda_4) u_L)$$

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$$F_{Ke} = \mu_1 F_1 - \mu_2 F_2$$

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$$\begin{cases} \mu_1 + \mu_2 = 1 \\ (a_1 + \Delta x^2) \mu_1 - (a_2 + \Delta x^2) \mu_2 = 0 \end{cases}$$

We obtain

$$F_{Ke} = |e| \kappa_e (\mu_1 (\lambda_1 + \lambda_2) u_K - \mu_2 (\lambda_3 + \lambda_4) u_L)$$

$$\text{with: } \begin{cases} \mu_1 = \frac{a_2 + \Delta x^2}{a_1 + a_2 + 2\Delta x^2}, \mu_2 = \frac{a_1 + \Delta x^2}{a_1 + a_2 + 2\Delta x^2}, \\ a_1 = \lambda_1 u_{M_1} + \lambda_2 u_{M_2}, a_2 = \lambda_3 u_{M_3} + \lambda_4 u_{M_4} \end{cases}$$

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